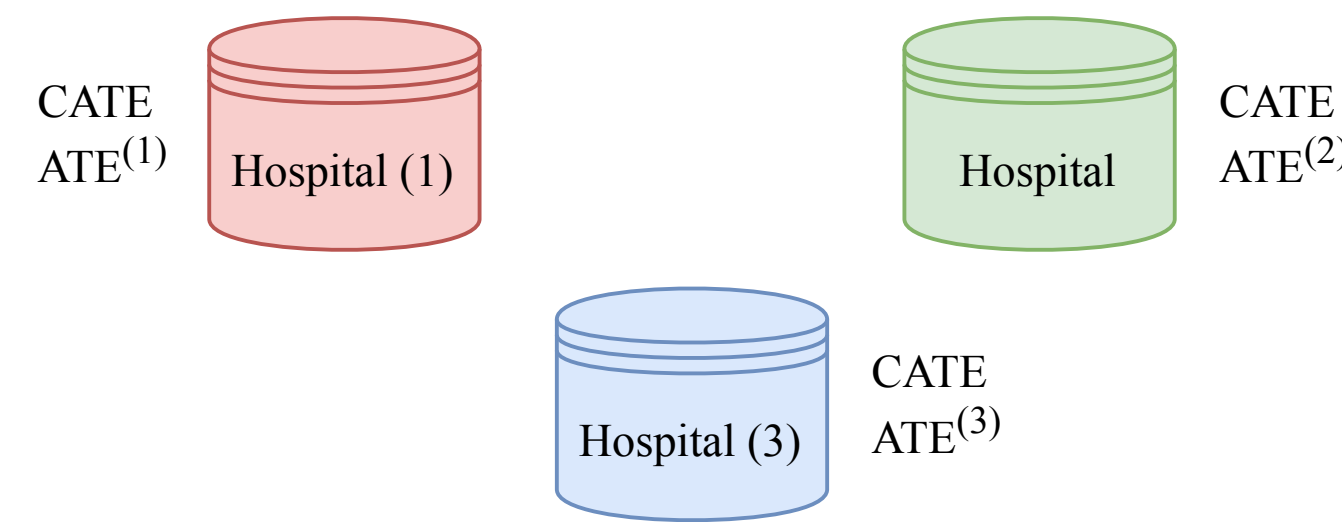


Contributions

- We propose CausalRFF that learns causal effects from multiple data sources while maintaining the sources at their local sites.
- CausalRFF minimizes information transmitted among the sources, thus enabling privacy-preserving causal inference.
- CausalRFF adaptively learns similarity of data distributions among the sources, and hence reduces negative transfer among them.
- The performance of CausalRFF is competitive to the baselines trained on combined data whose sources are dissimilar.

Motivation

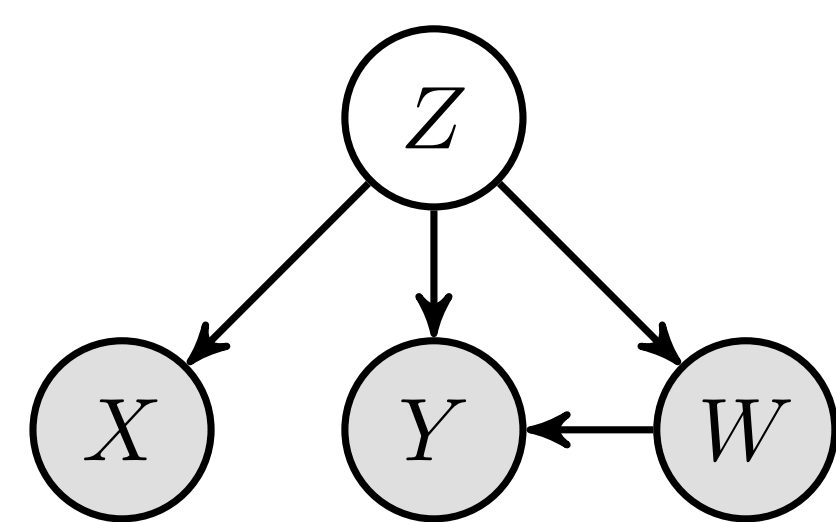
- Multiple data sources cannot be combined or shared due to privacy concern.
- Different data sources might have different data distributions.
- Some sources with sufficient data observations might dominate the ones with fewer data observations.



- For example: Patient data are private and confidential, and they are maintained in multiple hospitals.
- How to estimate causal effects from multiple sources without combining them?

Assumptions & Causal Quantities of Interest

The causal graph



- Z: latent confounder
- Y: the outcome
- W: the treatment
- X: covariate/proxy variable

- (1). Consistency: $W = w \implies Y(w) = Y$.
- (2). No interference + Positivity.
- (3). Individuals in all sources have the same set of *common* covariates.
- (4). Any individual does not exist in more than one source.

We estimate the following quantities:

- **Conditional average treatment effect (CATE):**

$$\tau(\mathbf{x}) := E[Y|\text{do}(W=1), X=\mathbf{x}] - E[Y|\text{do}(W=0), X=\mathbf{x}].$$

- **Average treatment effect (ATE):**

$$\tau := E[\tau(X)].$$

The Proposed Method

Expectation of the outcome given intervention on the treatment

$$E[y_i^s | \text{do}(w_i^s), \mathbf{x}_i^s]$$

The interventional distribution of the outcome

$$p(y_i^s | \text{do}(w_i^s), \mathbf{x}_i^s) = \int p(y_i^s | w_i^s, \mathbf{z}_i^s) p(\mathbf{z}_i^s | \mathbf{x}_i^s) d\mathbf{z}_i^s$$

The conditional distributions to be estimated

$$p(\mathbf{z}_i^s | \mathbf{x}_i^s, y_i^s, w_i^s), p(y_i^s | w_i^s, \mathbf{z}_i^s), p(w_i^s | \mathbf{x}_i^s) \& p(y_i^s | \mathbf{x}_i^s, w_i^s)$$

Augmented representer theorem estimator

Transfer kernel function

Allow dissimilar data distributions among the sources.

Random Fourier feature: enable federated training

$$k(\mathbf{u}, \mathbf{u}') \simeq \phi(\mathbf{u})^\top \phi(\mathbf{u}'),$$

$$\phi(\mathbf{u}) = B^{-\frac{1}{2}} [\cos(\omega_1^\top \mathbf{u}), \dots, \cos(\omega_B^\top \mathbf{u}), \sin(\omega_1^\top \mathbf{u}), \dots, \sin(\omega_B^\top \mathbf{u})]^\top,$$

where $\{\omega_b\}_{b=1}^B$ are drawn i.i.d from spectral distribution of the kernels.

Federated inference:

Repeat the following steps until convergence:

- (1). Compute gradients using local data and send to a server.
- (2). The server collects all *local* gradients and updates the model.
- (3). The server sends the new model to all sources.

Minimax lower bound: for learning distributions with latent confounders

$$\inf_{\hat{\theta}} \sup_{P \in \mathcal{P}} \mathbb{E}_P [\|\hat{\theta} - \theta(P)\|_2] \geq \frac{\sqrt{m(d_x + 3) \log(2\sqrt{m})}}{64\sqrt{B} \sum_{s \in \mathcal{S}} n_s (1 + \sum_{v \in \mathcal{S}, s} \lambda^{s,v})^2}.$$

Lower bound for the worst case of the best estimator. The bound shows how the sources are incorporated through the transfer factors $\lambda^{s,v}$.

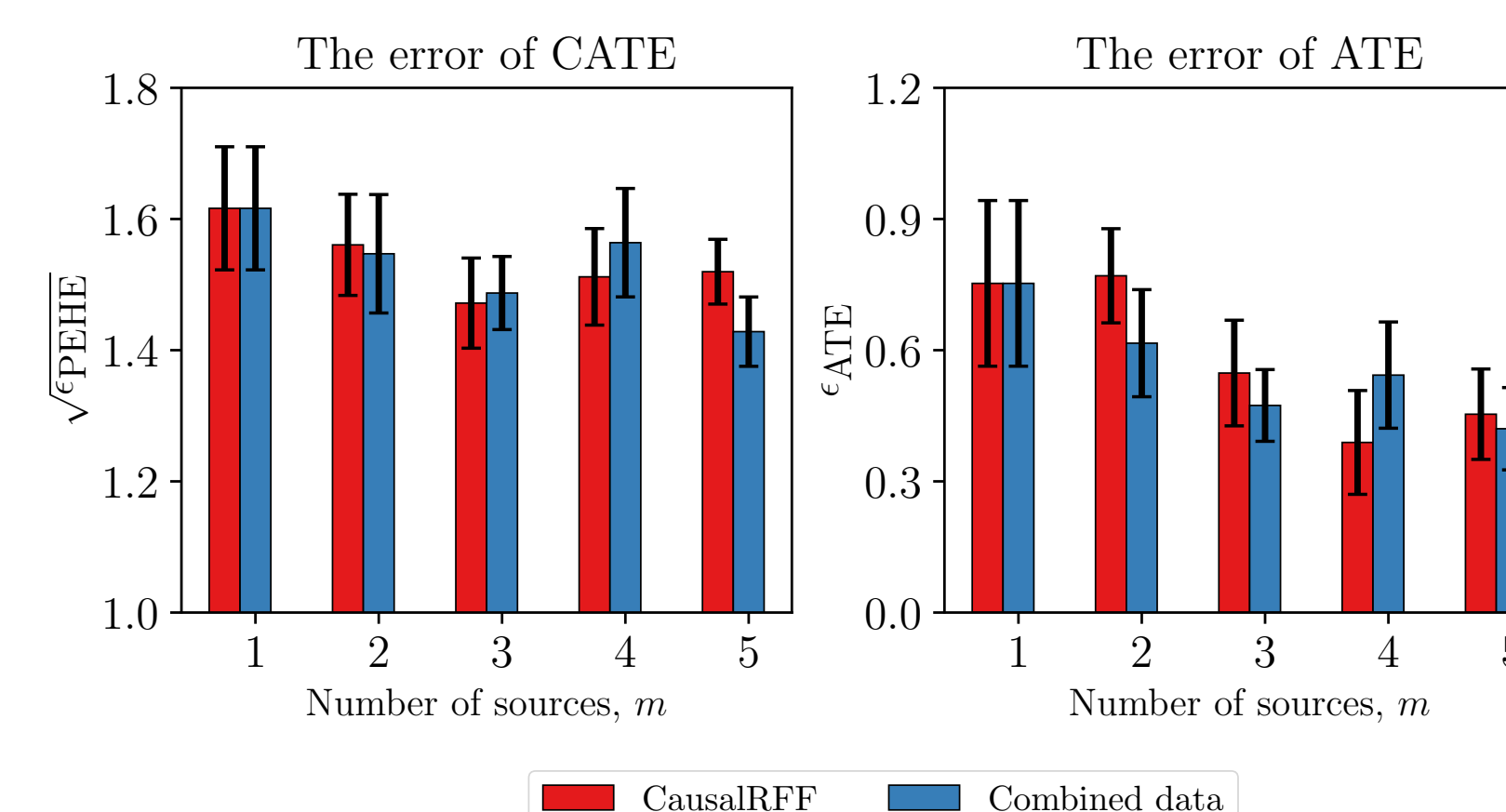
Experiments

Synthetic data

- The data are simulated with a ground truth causal model.
- We use a factor Δ to control for dissimilar data distributions.

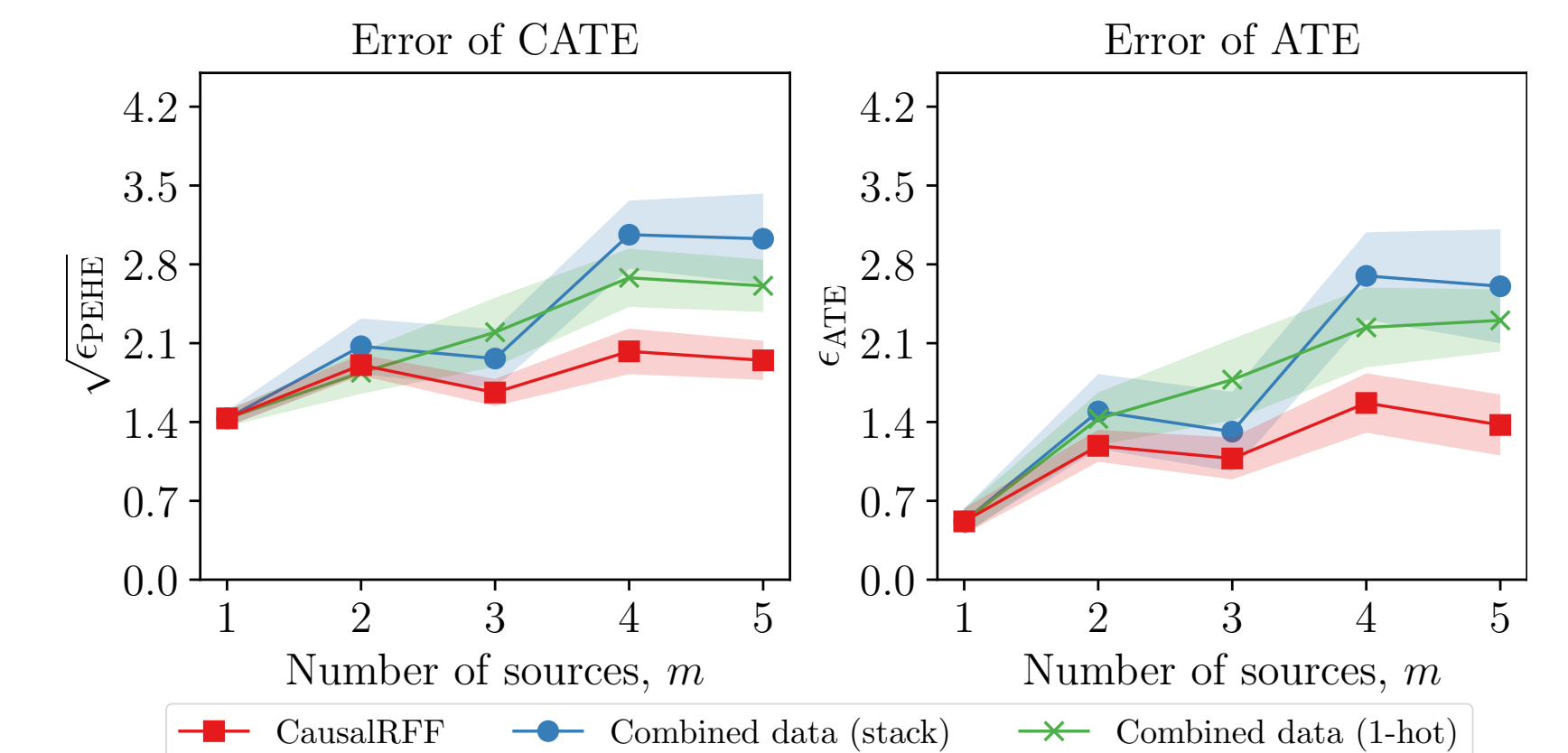
Analysis 1: The sources have the same data distribution ($\Delta = 0$).

Result: The errors of CausalRFF are as low as those of training on combined data. This result verifies the efficacy of CausalRFF for federated learning.



Analysis 2: The sources have different data distributions ($\Delta \neq 0$).

Result: The errors of CausalRFF are lower than those of training on combined data. This verifies the importance of CausalRFF when the sources have different data distributions.



IHDP dataset

- This dataset is from a study on the impact of specialist visits on the cognitive development of children.
- Treatment/control group are children with/without specialist visit.
- The dataset has 747 entries with 25 covariates, it is divided to 3 sources.

We compare with the recent baselines trained on combined data (cb):

Method	The error of CATE ($\sqrt{\epsilon_{PEHE}}$)			The error of ATE (ϵ_{ATE})		
	1 source	2 sources	3 sources	1 source	2 sources	3 sources
BART _{cb}	2.2±.22	2.1±.26	2.1±.25	1.0±.16	0.8±.20	0.7±.17
X-Learner _{cb}	1.9±.21	1.9±.21	1.8±.18	0.5±.21	0.5±.18	0.4±.11
R-Learner _{cb}	2.8±.31	2.6±.23	2.6±.17	1.6±.25	1.6±.26	1.6±.19
OthoRF _{cb}	2.8±.16	2.1±.14	1.9±.14	0.8±.15	0.6±.10	0.6±.10
TARNet _{cb}	3.5±.59	2.7±.12	2.5±.15	1.6±.61	0.7±.12	0.6±.17
CFR-wass _{cb}	2.2±.15	2.1±.22	2.1±.23	0.7±.23	0.6±.18	0.6±.16
CFR-mmd _{cb}	2.7±.19	2.3±.26	2.2±.10	0.9±.30	0.7±.17	0.5±.17
CEVAE _{cb}	1.8±.22	2.0±.11	1.7±.12	0.5±.14	1.4±.07	0.9±.07
FedCI	1.6±.10	1.6±.12	1.7±.09	0.5±.10	0.5±.24	0.5±.09
CausalRFF	1.7±.34	1.4±.33	1.2±.18	0.7±.14	0.7±.17	0.5±.16

Result: CausalRFF is among top-3 performance. Importantly, it preserves privacy under federated setting while the other baselines violate this constraint.

Conclusion & Future Work

- We proposed CausalRFF that learns causal effects without sharing raw data.
- CausalRFF is an important step towards a privacy-preserving causal learning model.
- Future research direction: Combining CausalRFF with differential privacy to give a stronger privacy guarantee.

Acknowledgement.

This research/project is supported by the National Research Foundation Singapore and DSO National Laboratories under the AI Singapore Programme (AISG Award No: AISG2-RP-2020-016).

AB was supported by an NRF Fellowship for AI grant (NRFRA1-2019-0002) and an Amazon Research Award.

This work was conducted while YL was at Harvard University and the views expressed here do not necessarily reflect the position of Roche AG.